

Wavelet Based Methods
for
Time Dependent PDEs

Mats Holmström

... Time Dependent PDEs

Partial differential equations, e.g., the Navier-Stokes equations in two dimensions:

$$\left\{ \begin{array}{lcl} \rho_t & = & -\rho_x u - \rho_y v - \rho(u_x + v_y) \\ u_t & = & -u u_x - v u_y + \frac{1}{\rho \text{Re}} ((2\mu + \lambda) u_{xx} \\ & & + (\mu + \lambda) v_{xy} + \mu u_{yy}) \\ & & - \frac{R}{\rho} (\rho_x T + \rho T_x) \\ v_t & = & -v v_y - u v_x + \frac{1}{\rho \text{Re}} ((2\mu + \lambda) v_{yy} \\ & & + (\mu + \lambda) u_{xy} + \mu v_{xx}) \\ & & - \frac{R}{\rho} (\rho_y T + \rho T_y) \\ T_t & = & -u T_x - v T_y - (\gamma - 1)(u_x + v_y) T \\ & & + \frac{\gamma k}{\rho \text{RePr}} (T_{xx} + T_{yy}) \\ & & + \frac{\gamma - 1}{\rho \text{Re} R} (\lambda(u_x + v_y)^2 + \mu(u_y + v_x)^2 \\ & & + 2\mu(u_x^2 + v_y^2)) \end{array} \right.$$

Discretization

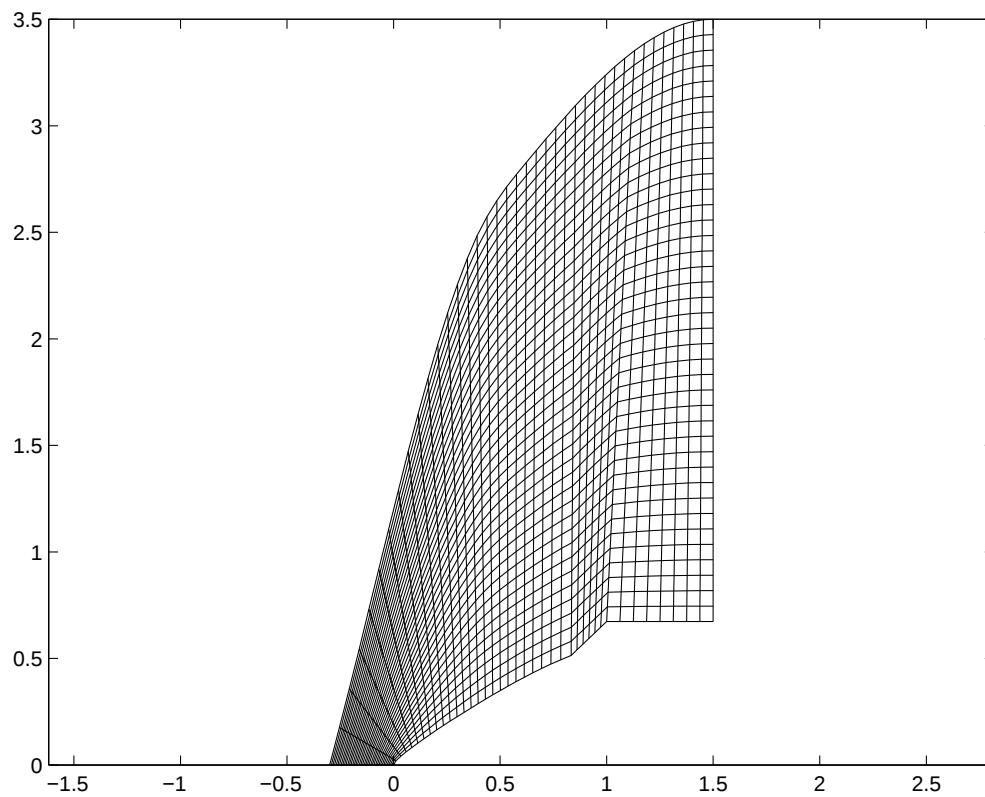


Figure 1: Two-dimensional grid

Approximate Solution

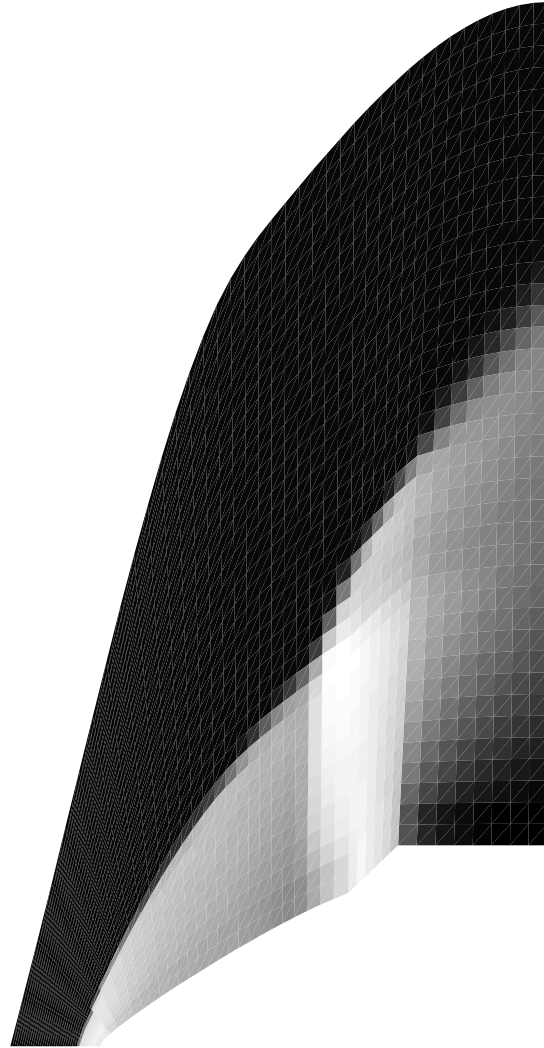


Figure 2: Temperature

Wavelet Based Methods ...

Position

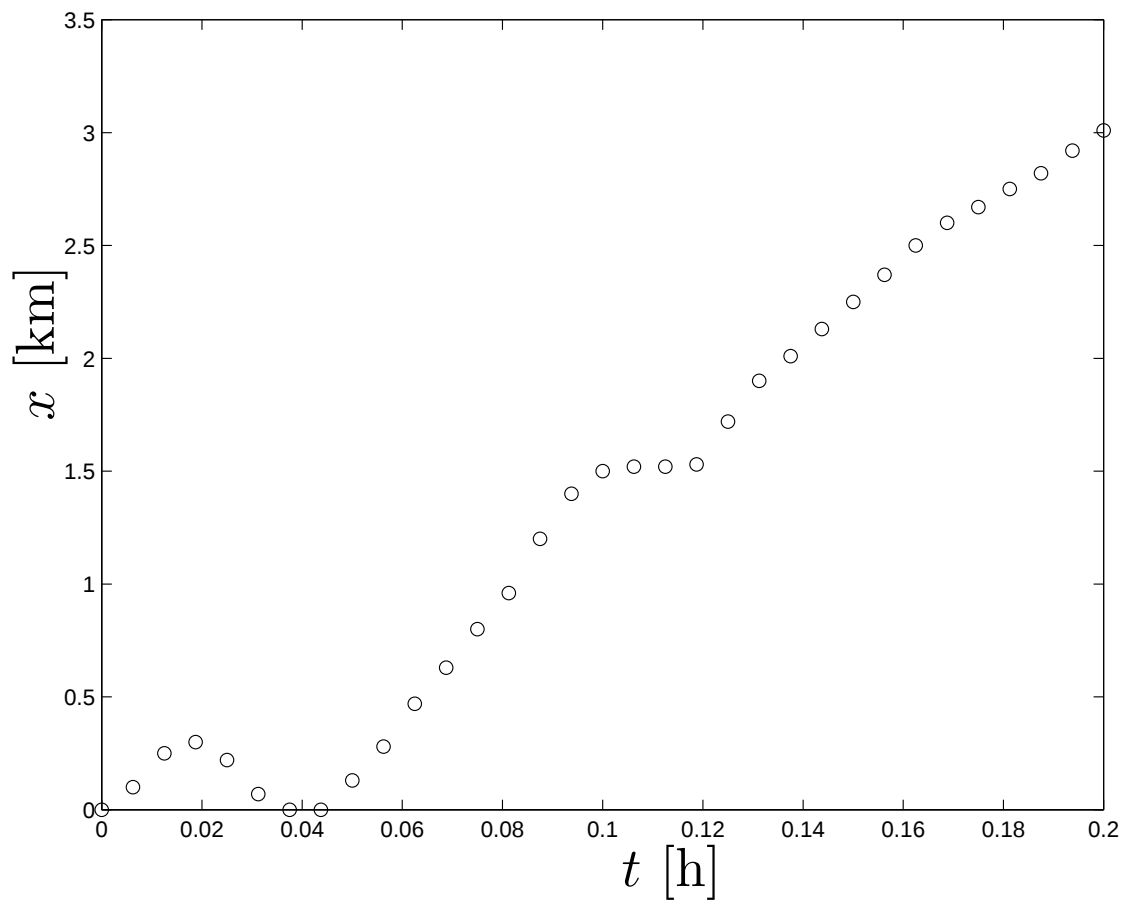


Figure 3: Position as a function of time

Differentiation

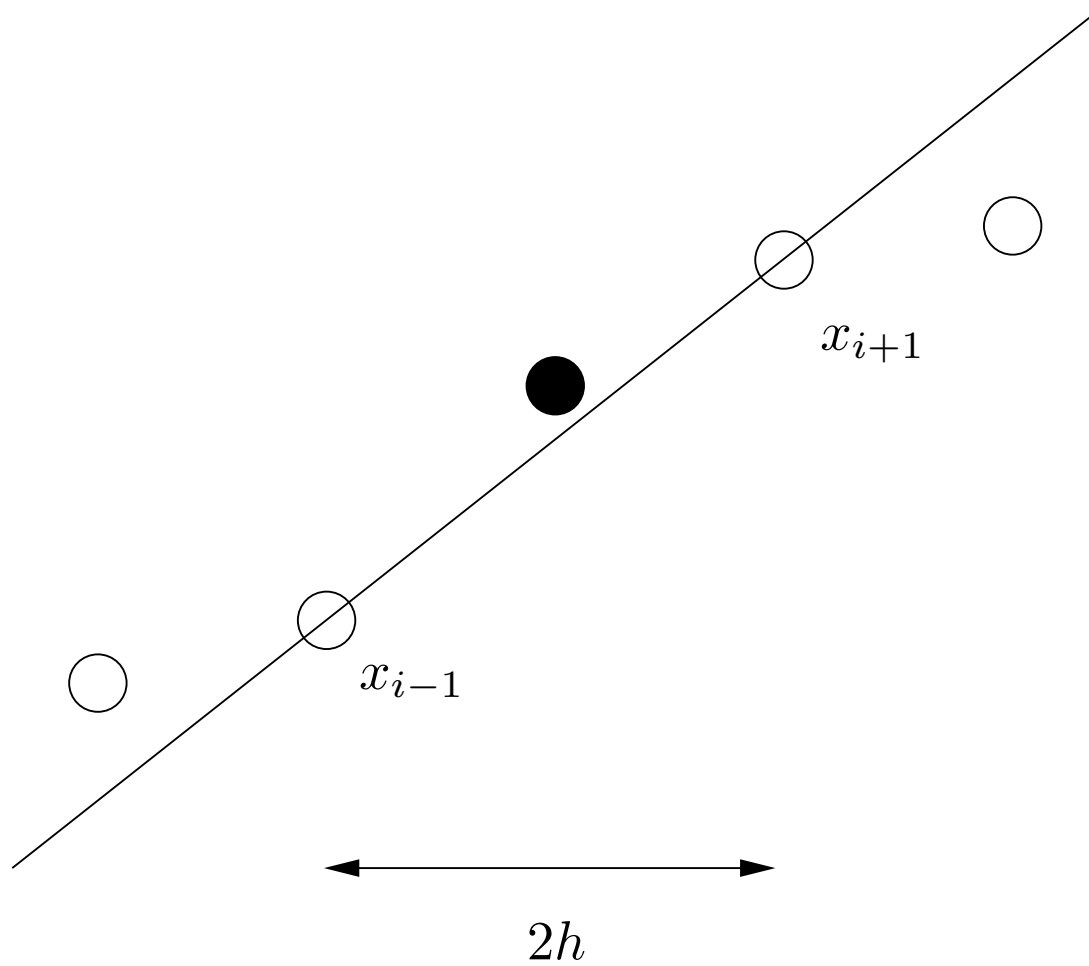


Figure 4: Approximation of the velocity

$$v \approx \frac{x_{i+1} - x_{i-1}}{2h}$$

Velocity

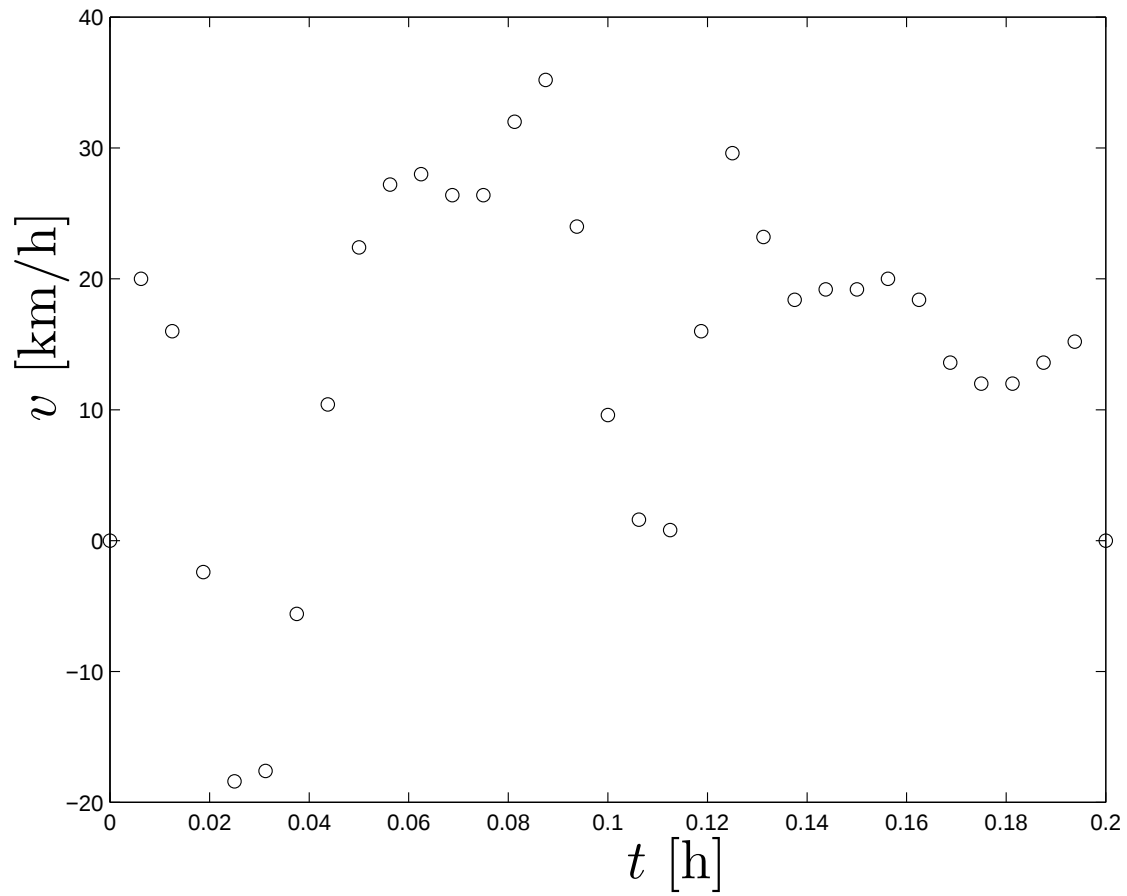


Figure 5: Velocity at all points

Interpolation

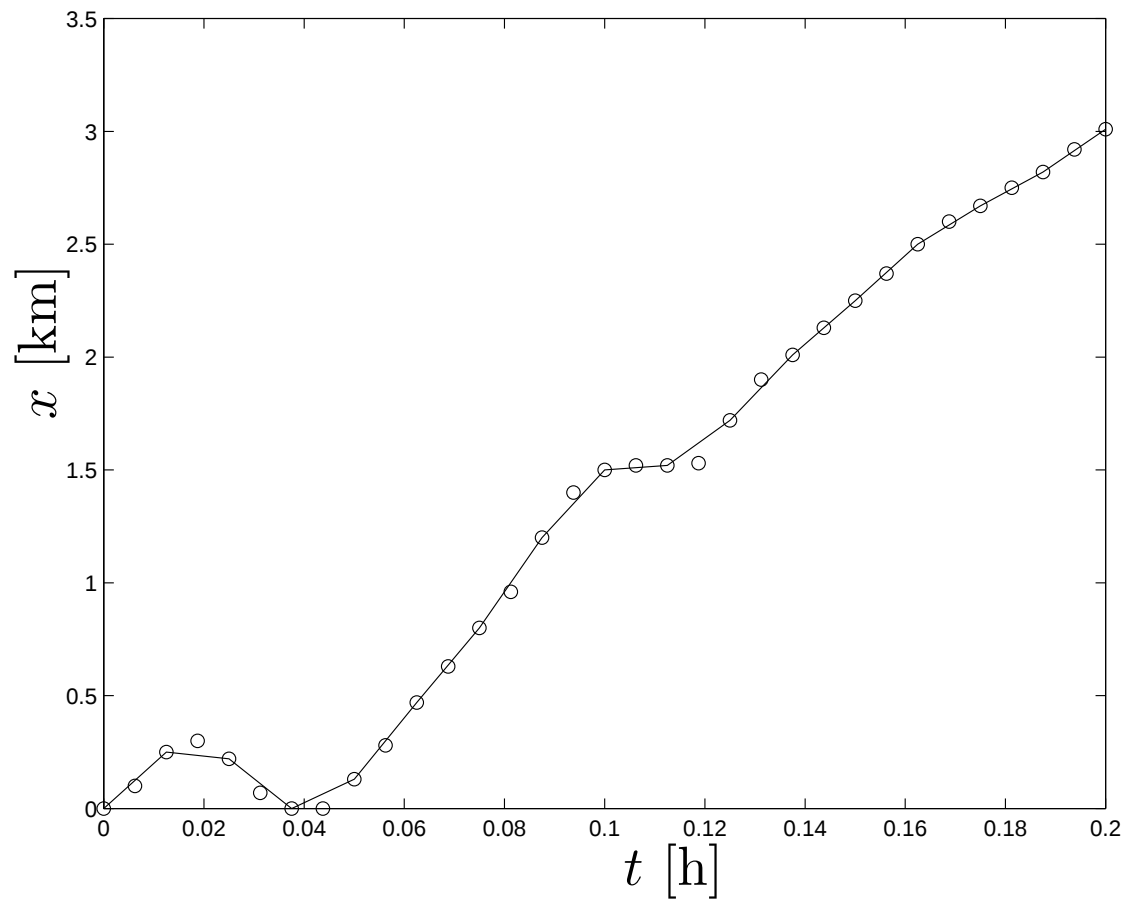


Figure 6: Skip every other point

Thresholding

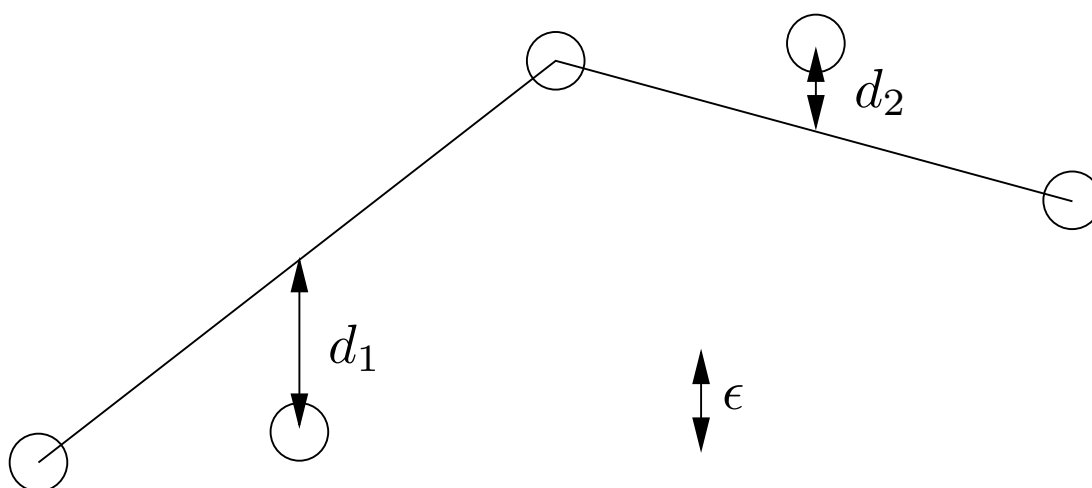


Figure 7: Remove point if $|d_i| < \epsilon$

Sparse Representation

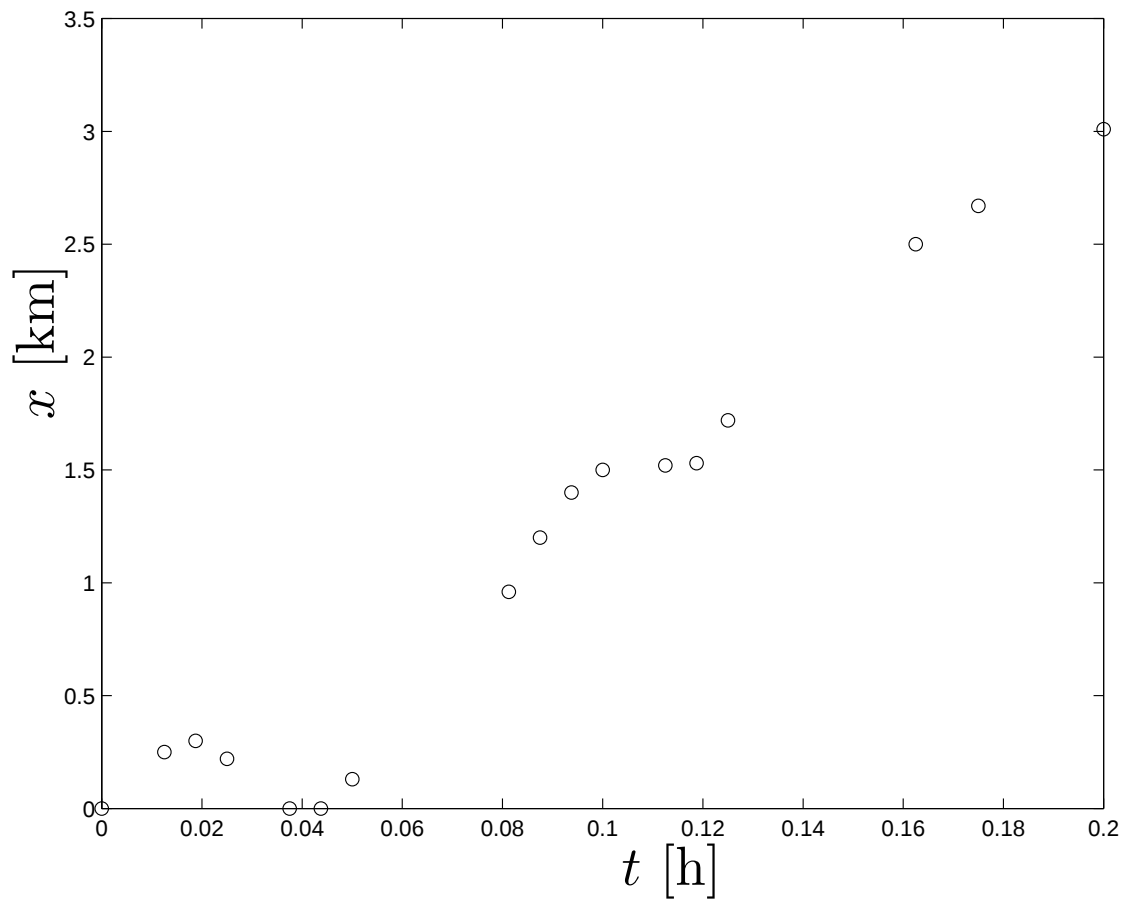


Figure 8: Sparse point representation

Reconstruction

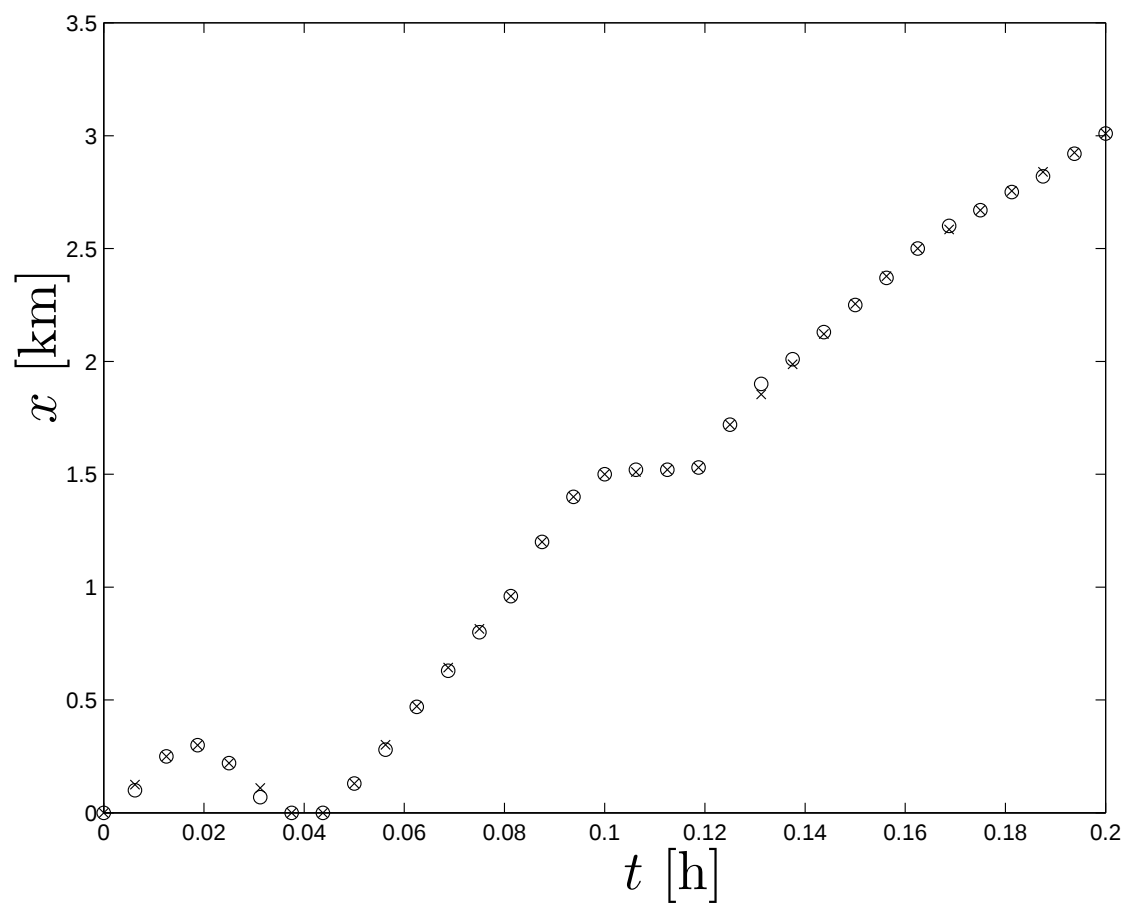


Figure 9: Reconstructed points

Sparse Velocity

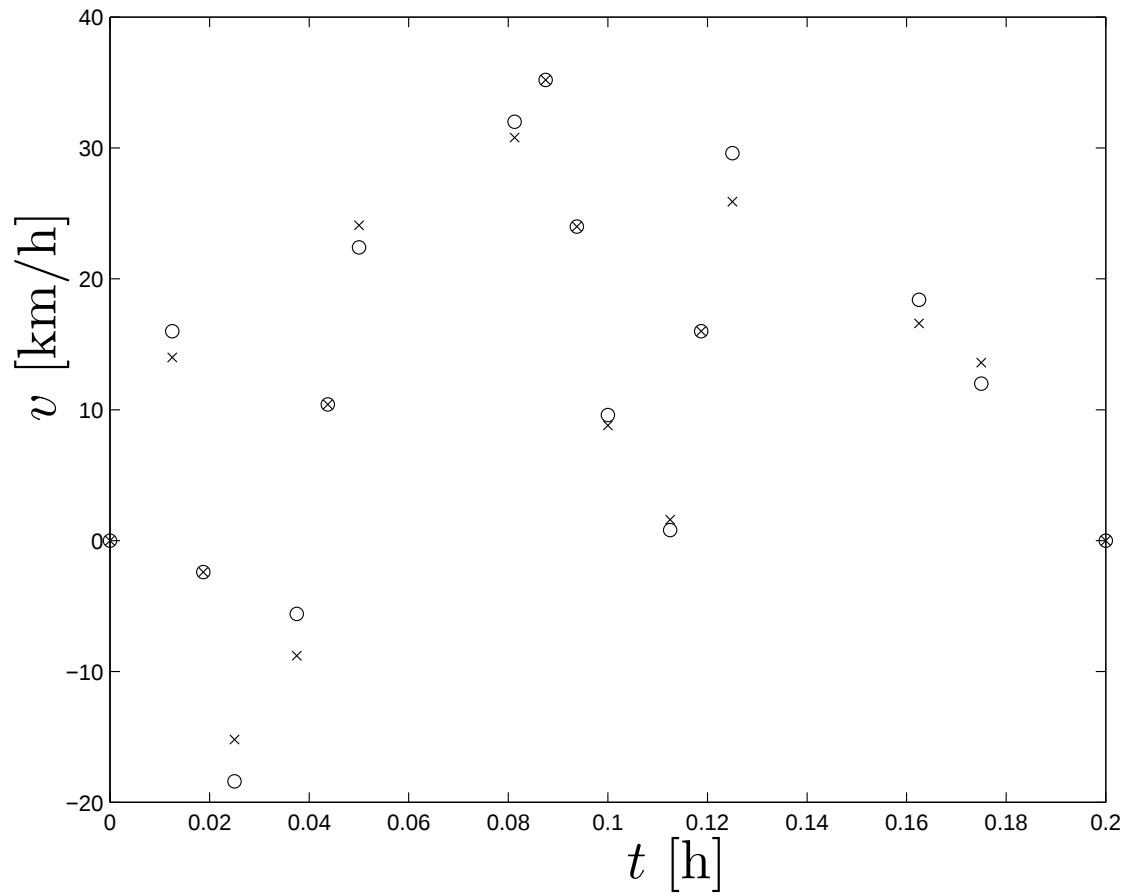


Figure 10: Velocity at the remaining points

Conclusions

A method for solving PDEs that saves

- computational time
- memory requirements